Behavioral/Systems/Cognitive

Robustness of a Rhythmic Circuit to Short- and Long-Term Temperature Changes

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Recent computational and experimental work has shown that similar network performance can result from variable sets of synaptic and intrinsic properties. Because temperature is a global perturbation that differentially influences every biological process within the nervous system, one might therefore expect that individual animals would respond differently to temperature. Nonetheless, the phase relationships of the pyloric rhythm of the stomatogastric ganglion (STG) of the crab, Cancer borealis, are remarkably invariant between 7 and 23°C (Tang et al., 2010). Here, we report that, when isolated STG preparations were exposed to more extreme temperature ranges, their networks became nonrhythmic, or “crashed”, in a reversible fashion. Animals were acclimated for at least 3 weeks at 7, 11, or 19°C. When networks from the acclimated animals were perturbed by acute physiologically relevant temperature ramps (11–23°C), the network frequency and phase relationships were independent of the acclimation group. At high acute temperatures (>23°C), circuits from the cold-acclimated animals produced less-regular pyloric rhythms than those from warm-acclimated animals. At high acute temperatures, phase relationships between pyloric neurons were more variable from animal to animal than at moderate acute temperatures, suggesting that individual differences across animals in intrinsic circuit parameters are revealed at high temperatures. This shows that individual and variable neuronal circuits can behave similarly in normal conditions, but their behavior may diverge when confronted with extreme external perturbations.

Introduction

Nervous systems must continuously balance their need for robustness with their ability to respond to changing internal and external environments. Theoretical and experimental evidence suggests that network performance can arise from many different underlying sets of intrinsic and synaptic conductances (Prinz et al., 2004; Marder and Goaillard, 2006; Schulz et al., 2006, 2007; Goaillard et al., 2009; Norris et al., 2011; Roffman et al., 2012). However, if neural circuits across animals have different sets of underlying parameters, to what extent can animals respond in a stereotyped and robust fashion to the environmental perturbations that they are likely to encounter in their normal environments (Grashow et al., 2009; Marder, 2011)?

For the neuronal circuits of cold-blooded organisms such as fish, worms, flies, and crabs, temperature poses a considerable challenge because temperature influences the reaction rates of all cellular processes (Cossins and Bowler, 1987; Neumeister et al., 2000; Lenz et al., 2005; Zhurov and Brezina, 2005; Szabo et al., 2008; Dillon et al., 2009; Garrity et al., 2010; Robertson and Money, 2012), including those that govern cellular excitability and synaptic transmission (Shoemaker et al., 1990; Johnson et al., 1991; Robertson, 1993; Robertson et al., 1996; Hille, 2001; Seeger et al., 2010; Dehghani et al., 2011). One possible way to achieve appropriate circuit function over a range of temperatures is to ensure that all of the processes that govern network performance have the same temperature dependence. Because this not the case, the question remains if, and to what extent, circuit stability is maintained when cold-blooded animals face temperature changes.

Here, we study the robustness of the well characterized pyloric rhythm of the crab, Cancer borealis, stomatogastric ganglion (STG) to temperature perturbation. Temperature is an ideal global perturbation with which to challenge the robustness and reliability of the networks of cold-blooded animals, such as crabs, for several reasons. First, crabs naturally experience significant temperature fluctuations in the wild (Donahue et al., 2009). Second, temperature is a global perturbation that influences the reaction rates of all biophysical parameters (Hille, 2001). Last, while temperature influences the reaction rates of all processes, it does not influence each process equally (Robertson and Money, 2012). This last fact is particularly important when considering how network performance is maintained in response to a global perturbation such as temperature change.

We previously demonstrated that the performance of the pyloric rhythm is remarkably robust to short-term temperature changes from 7 to 23°C (Tang et al., 2010). We further showed that this robustness benefits from similar, but not identical, Q10 values for several membrane currents.
In the present work, we studied populations of animals that were acclimated for >3 weeks to cold (7°C), medium (11°C), and warm (19°C) temperatures. We then determined how preparations from these populations responded to more extreme temperatures (24–31°C), thus revealing whether long-term temperature history alters the behavior of the pyloric network over a range of temperature that spans physiological and extreme conditions for the crab.

Materials and Methods

Adult male *C. borealis* were purchased from Commercial Lobster from years 2006 to 2010 and maintained in tanks containing artificial seawater for at least 3 weeks before use. The tanks were kept at 7 ± 1, 11 ± 1, or 19 ± 1°C. The complete stomatogastric nervous system (including the STG, the commissural ganglia, and the esophageal ganglion) was dissected out and pinned out in a Sylgard (Dow Corning)-coated plastic Petri dish containing chilled saline (11–12°C). Physiological saline was composed of the following (in mM): 440 NaCl, 11 KCl, 13 CaCl₂, 26 MgCl₂, 11 Trizma base, and 5 maleic acid, pH 7.4–7.5.

**Electrophysiology.** Extracellular recordings were made by placing Vaseline wells around nerves with stainless-steel pin electrodes placed in the wells and amplified using a differential amplifier (A-M Systems). For intracellular recordings, the STG was desheathed. Intracellular recordings were obtained from cell bodies in the STG using 10–30 MΩ glass microelectrodes pulled with a Flaming/Brown micropipette puller (Sutter Instrument). The microelectrode solution contained 0.65 M K₂SO₄, and 20 ms KCl. The temperature of the superfusing saline was controlled using a SC-20 Peltier device and a CL-100 temperature controller (Warner Instruments). For each preparation, temperature was held constant at 7°C for 300 s and increased by increments of 4°C up to 31°C (±0.5°C variability at fixed temperature). To reduce experimental variability, each preparation was given at least 5 min to adapt to a new steady-state temperature before measuring rhythm output. At the end of each experiment, preparations were brought down to 11°C. All data in this paper are from preparations that produced clearly robust pyloric rhythms when the temperature was returned to 11°C.

**Data acquisition and analysis.** Data were acquired using a Digidata 1200 data acquisition board (Molecular Devices) and analyzed using Clampfit 9.0 (Molecular Devices), Spike 6.0 (Cambridge Electronic Design), MATLAB (MathWorks), and SigmaPlot (SPSS, Inc.). Average burst-to-burst pyloric dilator (PD) onset time was used to quantify network frequency. Phase was measured as the time to burst onset/offset for each cell from PD onset, normalized by the cycle period. Temperature sensitivity was quantified using \( Q_{10} \). A temperature-dependent quantity (e.g., frequency) was fit to the following equation:

\[
R(T) = R_0 Q_{10}^{(T/T_0 - 10)}
\]

where \( R \) is the value of the quantity at temperature \( T \), \( R_0 \) is the value at the reference temperature, \( T_0 \) is the reference temperature, and \( Q_{10} \) describes the temperature sensitivity, and \( T_0 \) is the reference temperature. To find values for \( Q_{10} \), data were log-transformed and fit with a line.

**Quantification of robustness.** We created a “robustness index” (RI) to quantify the relative regularity of the pyloric rhythm at different temperatures. For these calculations, we used 295 s extracellular recordings of the pyloric dilator nerve (pdn), the gastropyloric nerve (gpn), and the pyloric nerve (py) that were first converted to PD, lateral pyloric (LP), and pyloric (PY) spike trains. The analysis consisted of three main steps, done on each spike train independently: (1) determination of the dominant frequency, (2) breaking the recordings up into short windows, and (3) performing an F test to characterize the spectral peaks.

**Step 1.** Although the pyloric rhythm can be quite irregular at high acute temperature, there is usually a discernable periodicity to it, reflected in a “bump” in the power spectrum between 0.5 and 6 Hz. We call this the “dominant frequency.” (For robust rhythms, the dominant frequency was equal to the pyloric frequency.) For later analysis, it is useful to rescale the time axis so that this peak occurs at \( f = 1 \) in the rescaled units. We determined the dominant frequency by calculating the power spectrum of the full 295 s trace, smoothing it, and automatically locating the peak between 0.5 and 6 Hz. We verified that this peak was consistent with any periodicity apparent in the spike trains. In 15 trials (of 172 presented here), automatic identification of the dominant frequency failed to give a plausible result, so we determined the dominant frequency by examining the power spectrum manually. Power spectra were calculated using Thompson’s direct multitaper method, with six windows, a time-bandwidth product equal to 4, and seven tapers, resulting in a frequency resolution of 0.081 Hz (Percival and Walden, 1993). Smoothing was done by convolving this spectrum with a Gaussian having SD equal to the frequency resolution.

**Step 2.** We wanted a measure that could be applied to short windows of data (1.5–15 s) because at higher temperatures the rhythms were often not stationary. We therefore rescaled the time base of each recording to put the dominant frequency at \( f = 1 \) in the rescaled units and chopped up the rescaled spike train into windows with a duration of 5 units. (For a robust rhythm, this would correspond to five cycles.)

**Step 3.** For each window, we then calculated the robustness index by detecting spectral “lines” (i.e., sharp peaks corresponding to a truly periodic component) in the power spectrum of each spike train (Percival and Walden, 1993). This produces an estimate of the amplitude of any such periodic component as a function of frequency, and a p value (based on an F statistic) at each frequency. This p value is small if that frequency is likely to contain a spectral line. We found the maximum amplitude between rescaled frequencies of \( 1/2 \) and 2, and based the robustness index on the p value at that frequency. These p values are being computed at many frequencies, however, so we applied a Sidak correction, where the number of comparisons is equal to the number of samples used to calculate the spectrum (\( N \)). This gives a corrected p value of \( p = 1 - (1 - p_{raw})^N \), where \( p_{raw} \) is original p value.

We wanted the robustness index to be higher for more regular rhythms, so our robustness index, RI, is given by the following: \( RI = 1 - p = 1 - (1 - p_{raw})^N \). Thus, the RI is always between 0 and 1, and RIs near 1 correspond to very robust rhythms, with RIs near 0 corresponding to the complete lack of a rhythm.

**Phase relationships.** While in many situations it is desirable to have the RI bounded by 0 and 1, in some cases this is inconvenient, because it implies that RIs near 1 (or 0) are unlikely to have a normal distribution. Therefore, in some cases, we subjected the RI to a log-odds transform and use the log-odds RI (LORI) as follows:

\[
LORI = \ln \frac{1 - p}{p} = \ln \frac{(1 - p_{raw})^N}{1 - (1 - p_{raw})^N}.
\]

The log-odds transform is commonly used in statistics to convert a quantity on the interval (0,1) to one that spans all possible real values, and is more likely to be normally distributed, or at least not to deviate as badly from normality. Note that the log-odds transformation is monotonic: if the RI of one preparation is larger than another, then the LORI will be larger also. A corrected p value of 0.05 corresponds to a per-window LORI of \( \sim 3 \), with smaller \( p \) values giving larger LORI scores. To calculate the overall LORI for the full 295 s record, we averaged all the per-window LORIs. This measure corresponds well to what inspection of the raw traces show: rhythms judged by eye to be more robust are very likely to have a higher RI, and therefore a higher LORI.

**Quantification of phase for irregular rhythms.** In addition to quantifying the robustness of the pyloric rhythm, we also quantified the variation in the phase relationships between the three pyloric cell types. Because this method had to work even when the pyloric rhythm was not robust, the method had to be independent of traditional measures that use detection of burst onset and offset. Consequently, we computed the coherence between spike trains to quantify phase relationships (Thomson and Chave, 1991; Percival and Walden, 1993; Rehm et al., 2008). Coherence is a spectral analog of the correlation coefficient. It is a complex quantity, with both a magnitude and a phase, and is a function of frequency; the magnitude is \( \leq 1 \). To calculate coherence between pairs of spike trains at the dominant frequency, we used Thomson’s direct multitaper method, with the same 295 s stretch of data used above, and the same time-bandwidth product and number of tapers.
Temperature acclimation of the pyloric rhythm

We previously studied the effects of temperature on animals that were held at 11°C and found that increases in temperature increased the frequency of the pyloric rhythm with a $Q_{10}$ of $2.3 \pm 0.2$ (SD), but the phase relationships were temperature invariant (Tang et al., 2010). We wondered whether acclimation of animals to different temperatures would change their responses to acute temperature changes. Therefore, we acclimated all of the animals in this study to temperatures of 7°C (n = 11), 11°C (n = 9), or 19°C (n = 12) for at least 3 weeks. These are temperatures well within the range that C. borealis experience in nature (Donahue et al., 2009). (For brevity, below we refer to these groups as cold-, mid-, and warm-acclimated, respectively.)

The responses of the cold- and warm-acclimated animals to acute temperature swings are shown in Figure 1, C and D. Within the “permissive” temperature range from 7 to 23°C, cold- and warm-acclimated animals responded similarly to each other, and to mid-acclimated animals (Tang et al., 2010). The pyloric rhythm frequency in the cold-acclimated animals increased approximately fourfold over this temperature range, from 0.73 ± 0.11 to 2.79 ± 0.34 (SD) Hz, with a $Q_{10}$ of 2.31 ± 0.30 (SD). For the warm-acclimated animals, the frequency also increased approximately fourfold, from 0.63 ± 0.13 to 3.03 ± 0.33 Hz, with a $Q_{10}$ of 2.78 ± 0.24. There were no significant differences in either the slope or y-intercept of the temperature dependence (when plotted on a log scale) between acclimation groups (p = 0.11 and p = 0.46, respectively, one-way ANCOVA; Fig. 1C). Mid-acclimated animals showed a $Q_{10}$ of 2.32 ± 0.20 for the pyloric frequency (Tang et al., 2010) and also showed no statistical difference from the other two acclimation groups.

Previous work on animals acclimated to 11°C showed that the phase relationships of the pyloric rhythm neurons were remarkably temperature invariant, meaning that all the onset and offset phases of each individual neuron exhibited $Q_{10}$ values approximately equal to 1 (Tang et al., 2010). Within the permissive temperature range, both the cold- and warm-acclimated animals also exhibited excellent temperature invariance of phase (Fig. 1D). Statistical significance across the acclimation groups was found for temperature dependence of LP onset and LP offset slopes (p < 0.05 and p < 0.01, one way ANCOVA, respectively), as well as for the y-intercept of the temperature dependence of the PD offset (p < 0.001, one way ANCOVA). These differences, while reaching statistical significance, were small and may not be functionally important for the animal. For all other values, no statis-

**Figure 1.** Quantification of pyloric network output for cold- and warm-acclimated animals at different acute temperatures. A, Connectivity diagram of the pyloric network containing the AB/PD, LP, and PY neurons. Resistor symbol signifies electrical coupling, and the black dots represent inhibitory synaptic connections. B, Example simultaneous extracellular nerve recordings of a robust pyloric rhythm at 19°C. The onset and offset delay of each neuron relative to the PD neuron are indicated. Note that in this example, PY burst is followed by spikes of another neuron, most clearly seen in third and fifth bursts. C, The pyloric network frequency of warm-acclimated (19°C; n = 12) and cold-acclimated (7°C; n = 11) animals plotted as a function of acute temperature. D, Mean phase (over many cycles) of pyloric cell onset and offset for the two acclimation groups plotted as a function of acute temperature. Error bars in C and D indicate SD.

To test the statistical significance of the variability in coherence as acute temperature was varied, we used Levene’s t test, in which each complex coherence was treated as a vector. For each acute temperature, the vector mean was calculated. The distance of each coherence from this vector mean was then squared, and the resulting values were used as surrogate data in a one-way ANOVA (Levene, 1960; Miller and Brown, 1997).

**Results**

The pyloric network of the STG generates rhythmic stomach movements that are important for the animal to digest food (Marder and Bucher, 2007). The pyloric circuit consists of a three-neuron pacemaker ensemble [the single anterior burster (AB) and two PD neurons], and the follower neurons, the LP, and the PY neurons (Fig. 1A, schematic connectivity diagram). The PD, LP, and PY neurons are active in a repeating triphasic motor pattern, in which the PD, LP, and PY neurons fire in alternation. This is seen in the extracellular recordings of the motor nerves from the STG (Fig. 1B). The activity of the PD neurons is seen on the pdn, the gpn carries the axon of the LP neuron, and the pyn shows the axons of the PY neurons.

By convention, the onset of the PD neuron burst is designated as the beginning of the pyloric rhythm cycle, and the onset/offset times of all other neurons are measured in reference to the PD neuron onset. One cycle period is defined as the time between the onset of one PD burst and the onset of the subsequent PD burst (Fig. 1B). The phase onset/offset of each neuron is defined as the delay to the onset/offset of each neuron divided by the cycle period.
tactical differences were found for slope and y-intercept across the two acclimation groups.

More extreme temperatures disrupt the pyloric rhythm
While functional circuit performance is robust for acute temperatures within the permissive range, at extreme temperatures one might expect that circuit performance will be disrupted due to different circuit component temperature sensitivities. Because each underlying circuit parameter may exhibit a different $Q_{10}$, it becomes more likely that the underlying circuit parameters will become incompatible as temperature is increased. We investigated this by increasing the acute temperature to the point at which the pyloric rhythm failed.

Although there were some individual preparations that generated robust triphasic pyloric rhythms up to 31°C, in general, the robustness of the pyloric circuit decreased after some critical temperature, particular to each animal. Figure 2A shows simultaneous intracellular recordings from the PD, LP, and PY (top three traces) and the corresponding extracellular recordings from the pdn, gpn, and pyn nerves (bottom three traces) in a single preparation, at temperatures from 19 to 31°C. At 19°C (Fig. 2A, first column), the pyloric band was still present for all three neurons, but the power of each individual neuron as a function of temperature. Figure 2B shows the spectrograms corresponding to the spike traces from Figure 2A. At 19°C (Fig. 2B, first panel), the spectrograms of the PD, LP, and PY neurons show high power at the pyloric frequency (−2 Hz; top, middle, and bottom spectrograms). A narrow red band indicates stable, periodic bursting, while a spread-out or fluctuating signal corresponds to weak, irregular bursting. Furthermore, the rhythmic activity was stable over time, as the power remained constant along the band for all three neurons. At 23°C (Fig. 2B, second panel), the power in the pyloric band was still present for all three neurons, but the power was noticeably weaker in the PD and LP neuron, and thus reflects a modest degradation in the robustness of the pyloric rhythm. At 27°C (Fig. 2B, third panel), the pyloric band was still present for the PD and PY neurons, but the LP neuron was completely lacking power in all frequencies for most of the record. The exceptions to these long stretches of silent activity were the small stretches of robust triphasic activity from ~0 to 25, 100 to 135, and 205 to 235 s. Finally, at 31°C (Fig. 2B, last panel), the spectrograms of the PD, LP, and PY neurons show relatively little power in the pyloric band, reflecting long periods of time in which the PD, LP, and PY neurons were silent (Fig. 2A).

Variability of activity patterns at high temperature
The robustness of circuit performance as a function of temperature varied within an individual, across individuals, and across acclimation groups. Several qualitatively different types of circuit failures were seen at extreme temperature ranges, some of which are displayed in Figure 3. At the boundaries between the permissive and nonpermissive temperature range, robust patterns of
Increased pyloric activity. In another preparation (Fig. 4, second column), when the temperature was returned to 27°C, the PD and LP neurons were silent but PY is tonic (recorded at 27°C; animal acclimated at 7°C). A fourth preparation (Fig. 4, fourth column) displayed relatively strong, but unstable power (i.e., a crash) behavior seen in STG preparations recovering from loss of modulatory inputs (Luther et al., 2003). In general, the spectrograms from the warm-acclimated group at this temperature showed relatively strong and stable power at the pyloric frequency band, with some fluctuations in the frequency. As the temperature was increased to 31°C, the power in the pyloric band became weaker and subsequently followed by another gradual decrease in frequency (Fig. 5, third column). Finally, when the temperature was increased again to 31°C, the resulting crash was remarkably similar to that seen in the previous exposure of the preparation to 31°C (Fig. 5, fourth column).

Effects of extreme temperature on circuit robustness

Examples of nonrobust pyloric motor patterns at extreme temperatures (>23°C). For A–D, PD, LP, and PY neuron activity obtained from simultaneous extracellular recordings exclusively (pdn, gpn, lvn, and pyn; top, middle, and bottom traces, respectively). A, An example of a robust pattern of activity that is interrupted intermittently by nonrobust activity in which PD and LP are silent but PY is tonic (recorded at 27°C; animal acclimated at 7°C). B, An example of irregular patterns of activity that resemble the boutting behavior that is observed in decentralized stomatogastric nervous systems (recorded at 27°C; animal acclimated at 7°C). C, An example of a semirobust pattern of activity in which the PD and PY neurons exhibit regular bursting behavior, but the LP neuron is relatively quiet (recorded at 27°C; animal acclimated at 7°C). D, An example of PD and LP neuron becoming silent, but PY becoming tonic (LP spikes are the largest ones on lvn, only two LP spikes are seen in this lvn trace; recorded at 27°C; animal acclimated at 7°C).

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Reversibility, stability, and reproducibility of crashes

One potential explanation for the failures in network performance at high temperatures is irreversible neuronal heat damage. To determine whether this was the case, we repeatedly heated and cooled individual preparations from a permissive temperature to a crash-inducing temperature. An example of this is shown in Figure 5. At 23°C (Fig. 5, first column), the PD, LP, and PY neurons were in typical pyloric time. However, when the temperature was raised to 31°C, the preparation crashed. This was reflected in the lack of power in the PD, LP, and PY neuron spectrograms, with the exception of two short 10–20 s episodes of robust activity spaced ~150 s apart from one another (Fig. 5, second column). When the temperature was returned to 27°C, the PD, LP, and PY neurons resumed their robust pattern of activity (Fig. 5, third column). Finally, when the temperature was increased again to 31°C, the resulting crash was remarkably similar to that seen in the previous exposure of the preparation to 31°C (Fig. 5, fourth column).

To quantitatively evaluate functional circuit operation at different temperatures, we devised the RI, which quantifies the robustness of rhythmic activity in each individual neuron (see Materials and Methods). Figure 5 shows a number of spectrograms with their associated RI traces. As can be seen, RI values near 1 indicate robust pyloric-timed activity, while values near 0 indicate activity with little rhythmicity.
Robustness of circuit performance

The RI is a useful and intuitively appealing measurement but has unwieldy statistical properties. We therefore used a log-odds transform of the RI (LORI) (see Materials and Methods) to perform statistical comparisons of robustness across preparations. Cold-acclimated preparations were highly robust at moderate acute temperatures, but their robustness tended to decrease above 23°C (Fig. 6A). Mid-acclimated animals also were robust at

Figure 6. Spectrograms of activity in the PD, LP, and PY neurons as a function of temperature from cold- and warm-acclimated animals. Each spectrogram block spans 0 – 6 Hz on the y-axis and 300 s on the x-axis; the color is normalized to maximum power of each individual preparation. A–E, The spectrograms of network activity from the PD, LP, and PY neurons from cold-acclimated animals (7°C) as a function of temperature from 15 to 31°C. F–I, Spectrograms of network activity from warm-acclimated animals (19°C) plotted as a function of temperature from 15 to 31°C. Only temperatures recorded from 15 to 31°C are displayed for clarity. The missing spectrogram block (E, 31°C) is missing because that preparation crashed at 27°C, and therefore the temperature was not raised further.
moderate temperatures but tended to stay more robust at high temperatures (Fig. 6B). Warm-acclimated animals showed an even stronger tendency to remain robust at high temperatures (Fig. 6C). For the PD neuron, we found significant effects of acute temperature (p < 10^-4) and acclimation group (p < 0.001), and a significant interaction between these treatments (p < 10^-4, two-way repeated-measures ANOVA). Furthermore, while all three acclimation groups showed a significant decline in robustness from 19 to 31°C (p < 0.01 for all three, unpaired t test), the robustness at 31°C was significantly lower for the cold-acclimated group (Fig. 6D, top; p < 0.05 for warm vs cold and mid vs cold, unpaired t test). Similar results were obtained for the LP and PY neurons (Fig. 6D, middle and bottom). For the PY neuron, there was a nonsignificant main effect of acclimation group on robustness (p = 0.77), but there was still a significant interaction between acute temperature and acclimation group (p < 10^-4, two-way repeated-measures ANOVA). Additional statistical tests are summarized in Figure 6D.

Animal-to-animal variability of rhythm dynamics
Within acclimation groups, the variability in the phase of the pyloric neurons increased with temperature. The irregularity in the bursts of the three cells at a given temperature was quantified by measuring the coherence phase between each cell pair (PD–LP, LP–PY, PY–PD; Fig. 7). This generated two values for each cell pair at each temperature: a coherence magnitude (from 0 to 1) that captures how correlated activity in the two neurons is at the pyloric frequency, and a coherence phase that loosely captures the phase difference between the centers of the bursts of the neurons. Rhythms with high coherence are shown as dots closer to the outer rim of the unit circle. The higher the variability across animals at a certain temperature, the more the dots are spread out around the phase circle.

In the cold-acclimated group, the PD–LP and the LP–PY coherence showed a significant effect of acute temperature on variance (p < 0.05, Levene’s s test). In the warm-acclimated group, the LP–PY and PY–PD coherence also displayed a significant effect of acute temperature on variance (p < 0.05, Levene’s s test). The middle-acclimated group had no statistically significant change in coherence variability with temperature, yet irregularity in the phase and coherence can still be seen at various temperatures.
Discussion

In this work, we used acute and long-term temperature modifications to determine the extent to which individual animals responded in a stereotyped fashion to a global environmental perturbation. Considerable evidence now argues that individual animals vary considerably in the parameters that govern network performance, although they can produce reliable behaviors (Golowasch et al., 1999b, 2002; Goldman et al., 2001; Prinz et al., 2004; Schulz et al., 2006, 2007; Tobin and Calabrese, 2006; Goaillard et al., 2009; Taylor et al., 2009; Tobin et al., 2009; Prinz, 2010; Roffman et al., 2012). Although multiple solutions can be consistent with “good enough” performance (Marder and Goaillard, 2006; Marder, 2011; Marder and Taylor, 2011), most individuals in the population must nevertheless respond robustly to the environmental perturbations that they typically encounter. The crabs used in this study, *C. borealis*, live in the Atlantic Ocean and routinely encounter substantial temperature fluctuations, so these experiments are essentially probing the extent to which these animals can deal with one of the most salient challenges of their natural environment.

We were surprised to discover that acclimation of animals to different temperatures did not change the frequency and phase relationships of the pyloric rhythms measured at any given temperature, especially so because temperature acclimation of the lobster, *Homarus americanus*, resulted in shifts in the frequency–temperature relationship of the heart rate (Camacho et al., 2006). Because the frequency of the pyloric rhythm at 19°C is more than twice as fast as at 7°C (Tang et al., 2010), we predicted that acclimation would shift the temperature–frequency relationship of the pyloric rhythm. This expectation was not unreasonable based on previously published data (Golowasch et al., 1999b, 2002; Goldman et al., 2001; Prinz et al., 2004; Schulz et al., 2006, 2007; Tobin and Calabrese, 2006; Goaillard et al., 2009; Taylor et al., 2009; Tobin et al., 2009; Prinz, 2010; Roffman et al., 2012). However, our results suggest that the pyloric rhythm may be less sensitive to temperature changes than previously thought.

![Figure 7](image-url)  
Figure 7. Phase coherence between pairs of pyloric neuron spike trains versus acute temperature, for preparations acclimated to different temperatures. The outer rim of each circle represents a coherence magnitude of 1. The phase angle for each point captures the average distance in phase between the centers of two cell type bursts. The phase is plotted, as the first cell type leading the second, going counterclockwise starting at the right-most point on the circle. Each color represents a different preparation. The black crosses represent the mean coherence phase within each group. The rows with gray backdrop displayed significantly different variance across acute temperature ($p < 0.05$, Levene’s test) (see Materials and Methods).
on evidence from a number of studies showing that neurons homeostatically adjust their firing rates, either through intrinsic or synaptic mechanisms (or both), in response to chronic increases or decreases in neuronal activity (Thoby-Brisson and Simmers, 1998, 2000, 2002; Desai et al., 1999; Pratt et al., 2003; Pratt and Aizenman, 2007). That acclimation did not cause such a shift suggests that the pyloric network frequency may not be a crucial controlled variable for homeostatic regulation, although it is often (and sometimes implicitly) assumed that the set point is related in a simple manner to frequency (LeMasson et al., 1993; Liu et al., 1998; Golowasch et al., 1999a). When the descending modulatory inputs to the STG are removed, the pyloric rhythm usually stops, but recovers over the next several days, but at a lower frequency (Thoby-Brisson and Simmers, 1998; Golowasch et al., 1999a). Thus, we now speculate that the alternating triphasic pattern of the pyloric rhythm, rather than its frequency, could be the target of homeostatic regulation.

All of the animals in this study were acclimated for at least 3 weeks. Previous work in crustaceans, on numerous physiological processes, showed that most regulatory processes come to steady state after 2 weeks of acclimation (Zecević and Levitan, 1980; Lagerspetz, 1994; Camacho et al., 2006). Some crabs were acclimated for as long as 6 weeks, and preparations from these animals gave data consistent with those from the 3-week-acclimated animals. Therefore, it appears that the 3 week acclimation times we used were sufficient to produce whatever acclimation-induced changes were likely to occur.

While the pyloric rhythm is very robust over a wide temperature range, “crashes”—periods of time during which the pyloric rhythms were disrupted—were apparent when the temperature was increased to values higher than crabs routinely experience. Because the rate of each enzymatic or ion channel process increases exponentially with temperature, even slightly different temperature dependencies between two compensatory cellular processes will cause the rates of those processes to become unmatched at extreme temperatures. It then follows that, as temperature is increased to the point where the cellular processes are no longer adequately matched to each other, circuit performance can be expected to degrade, perhaps catastrophically, resulting in a crash.

Nevertheless, if all pyloric circuits had similar parameters, one would expect all of them to crash in more-or-less the same way. But if pyloric circuit parameters differ markedly across individuals, as previous data argue (Golowasch et al., 1999b; Marder and Gouaillard, 2006; Schulz et al., 2006, 2007; Gouaillard et al., 2009), one would expect preparations from different animals to crash in different ways. Thus, degraded circuit performance at extreme temperatures provides a way to distinguish whether the underlying parameters of individual pyloric circuits are diverse, or are highly constrained.

Qualitatively, we found that individual circuits crashed at different temperatures, to different extents, and/or in different ways at extreme temperatures (Figs. 4, 7). In general, these results are consistent with the notion that the circuits from individual animals are composed of different sets of underlying parameters that confer good enough solutions (Prinz et al., 2004; Marder and Gouaillard, 2006; Marder, 2011). Thus, these data provide experimental validation for this theoretical notion at the circuit level.

Quantitatively, while temperature acclimation did not induce changes in network frequency or phase relationships, it did produce alterations in the robustness of circuit performance at extreme temperatures. In response to acute increases in temperature, disruption of circuit performance occurred at lower temperatures in cold-acclimated animals than in warm-acclimated animals (qualitatively, Fig. 4; quantitatively, Fig. 6). We interpret these results as a shift in the operational regime of good enough solutions for appropriate network behavior. We suggest that acclimation induces an alteration in underlying conductance parameters and moves the circuit toward the “center” of good enough solutions and thus further from the boundary between good enough solutions and crashed solutions. Importantly, this alteration of parameters must occur in such a way as to maintain robust and consistent circuit performance in the permissive temperature range.

The observation that acclimation shifts the operational range of circuit performance is consistent with long-known behavioral experiments in locomotion performance of fish (Robertson and Money, 2012) and more recent results in the lobster heart (Worden et al., 2006). In the case of the Homarus americanus heart, warm acclimation shifted the upper limit for cardiac function from 24 to 29°C (Worden et al., 2006). The results reported in this paper are particularly intriguing because acclimation shifted the limits of robust network performance without changing its behavior over the permissive temperature range.

Increasing evidence suggests that variability in underlying system components is a basic feature of all organisms, including Escherichia coli and yeast (Elowitz et al., 2002; Korobkova et al., 2004; Stolovich et al., 2006; Emonet and Cluzel, 2008; Eldar and Elowitz, 2010; Dufour et al., 2011; Stolovich and Braun, 2011; Sneddon et al., 2012), where variability in gene expression and in the concentrations of molecular constituents are thought to allow cells to explore parameter space and to respond appropriately to changing external conditions.

In complex nervous systems, variability can be an important contributor to system performance and robustness (Padmanabhan and Urban, 2010). For example, in songbirds, there is a neural circuit that generates variability in vocal performance (Kao et al., 2008). This variability is important for motor exploration and vocal plasticity and also for enabling animals to respond to changing external conditions such as social context (Stepanek and Doupe, 2010).

In summary, these experiments demonstrate that, although individual animals can differ considerably in the number of ion channels and receptors expressed in a circuit important for survival, they can nonetheless show robust and stereotyped responses to a physiologically relevant environmental perturbation. Nonetheless, more extreme perturbations reveal the essential differences between animals, demonstrating that some members of the population will be more successful than others in responding to extreme environmental conditions. Thus, the variability among individuals in the population may be useful for allowing the species to be successful under different kinds of environmental stresses.

References
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